

**GOVT. POLYTECHNIC KANDHAMAL, (PHULBANI)**

**LESSON PLAN: CONTROL SYSTEM**

**6<sup>TH</sup> – SEMESTER, 2026 (S)**

Discipline: <b>Electrical Engineering</b>	Semester: <b>Summer 2026</b>	Name of the teaching faculty: <b>BICHITRANANDA PADHIARY, Lect.I (Electrical)</b>
Subject: <b>CSE</b>	No of days/per week class allotted: <b>05</b>	Semester From Date: <b>22.12.2025</b> To Date: <b>18.04.2026</b> No of weeks: <b>16</b>
Week:	Class day:	<b>Theory/practical topics:</b>
<b>1<sup>ST</sup></b>	<b>1<sup>ST</sup></b>	<b>Unit I (Fundamental of Control System)</b> Classification of Control system , Open loop system & Closed loop system and its comparison
	<b>2<sup>ND</sup></b>	Effects of Feed back
	<b>3<sup>RD</sup></b>	Standard test Signals(Step, Ramp, Parabolic, Impulse Functions)
	<b>4<sup>TH</sup></b>	Servomechanism
	<b>5<sup>TH</sup></b>	<b>Unit-II(Mechanical Model of System)</b> Transfer Function & Impulse response, Properties, Advantages & Disadvantages of Transfer Function
<b>2<sup>ND</sup></b>	<b>1<sup>ST</sup></b>	Poles & Zeroes of transfer Function
	<b>2<sup>ND</sup></b>	Simple problems of transfer function of network.
	<b>3<sup>RD</sup></b>	Mathematical modeling of Electrical Systems(R, L, C, Analogous systems)
	<b>4<sup>TH</sup></b>	<b>Unit-III(Control System Components)</b> Components of Control System
	<b>5<sup>TH</sup></b>	Gyroscope, Synchros
<b>3<sup>RD</sup></b>	<b>1<sup>ST</sup></b>	Tachometer, DC servomotors, Ac Servomotors.
	<b>2<sup>ND</sup></b>	Revision of Control System Components
	<b>3<sup>RD</sup></b>	<b>CLASS TEST-I</b>
	<b>4<sup>TH</sup></b>	<b>Unit-IV(Block Diagram Algebra and Signal Flow Graph)</b> Definition: Basic Elements of Block Diagram ,Canonical Form of Closed loop Systems
	<b>5<sup>TH</sup></b>	Rules for Block diagram reduction
<b>4<sup>TH</sup></b>	<b>1<sup>ST</sup></b>	Procedure for of Reduction of Block Diagram
	<b>2<sup>ND</sup></b>	Simple Problem for equivalent transfer function
	<b>3<sup>RD</sup></b>	Basic Definition in Signal Flow Graph & properties
	<b>4<sup>TH</sup></b>	Construction of Signal Flow graph from Block diagram
	<b>5<sup>TH</sup></b>	Mason's Gain formula
<b>5<sup>TH</sup></b>	<b>1<sup>ST</sup></b>	Simple problems in Signal flow graph for network
	<b>2<sup>ND</sup></b>	<b>Unit-V (Time Response Analysis)</b> Time response of control system

	3 <sup>RD</sup>	Standard Test signal. 1. Step signal, 2. Ramp Signal
	4 <sup>TH</sup>	3. Parabolic Signal 4. Impulse Signal
	5 <sup>TH</sup>	Time Response of first order system with: 1. Unit step response 2. Unit impulse response
6 <sup>TH</sup>	1 <sup>ST</sup>	Time response of second order system to the unit step input. 1. Time response specification. 2. Derivation of expression for rise time, peak time, peak overshoot, settling time and steady state error
	2 <sup>ND</sup>	3. Steady state error and error constants
	3 <sup>RD</sup>	Types of control system.[ Steady state errors in Type-0, Type-1, Type-2 system]
	4 <sup>TH</sup>	Effect of adding poles and zero to transfer function.
	5 <sup>TH</sup>	Response with P, PI, PD and PID controller.
7 <sup>TH</sup>	1 <sup>ST</sup>	Simple Numerical and Doubt Clearing Class
	2 <sup>ND</sup>	<b>Unit-VI(ANALYSIS OF STABILITY BY ROOT LOCUS TECHNIQUE.)</b> Root locus concept
	3 <sup>RD</sup>	Construction of root loci.
	4 <sup>TH</sup>	Construction of root loci and numerical
	5 <sup>TH</sup>	Numerical on construction of root locus
8 <sup>TH</sup>	1 <sup>ST</sup>	Rules for construction of the root locus.
	2 <sup>ND</sup>	Numerical on root locus
	3 <sup>RD</sup>	Numerical on root locus
	4 <sup>TH</sup>	Effect of adding poles and zeros to $G(s)$ and $H(s)$ .
	5 <sup>TH</sup>	Numerical on Poles and Zeros
9 <sup>TH</sup>	1 <sup>ST</sup>	Revision and Simple numerical.
	2 <sup>ND</sup>	<b>Unit-VII(FREQUENCY RESPONSE ANALYSIS.)</b> Correlation between time response and frequency response
	3 <sup>RD</sup>	Polar plots
	4 <sup>TH</sup>	Numerical on Polar Plots
	5 <sup>TH</sup>	Bode plots.
10 <sup>TH</sup>	1 <sup>ST</sup>	Simple numerical on Bode Plots
	2 <sup>ND</sup>	All pass and minimum phase system
	3 <sup>RD</sup>	Computation of Gain margin and phase margin
	4 <sup>TH</sup>	Numerical on Phase margin and gain margin
	5 <sup>TH</sup>	Log magnitude versus phase plot.
11 <sup>TH</sup>	1 <sup>ST</sup>	Closed loop frequency response
	2 <sup>ND</sup>	<b>Unit-VIII(NYQUIST PLOT )</b> Principle of argument
	3 <sup>RD</sup>	Nyquist stability criterion
	4 <sup>TH</sup>	Nyquist stability criterion applied to inverse polar plot.

	5 <sup>TH</sup>	Simple Numerical on Nyquist Criterion.
12 <sup>TH</sup>	1 <sup>ST</sup>	Effect of addition of poles and zeros to G(S) H(S) on the shape of Nyquist plot.
	2 <sup>ND</sup>	Methods of Starting of Synchronous Motor
	3 <sup>RD</sup>	Assessment of relative stability
	4 <sup>TH</sup>	Constant M and N circle
	5 <sup>TH</sup>	Nicholas chart.
13 <sup>TH</sup>	1 <sup>ST</sup>	Simple numerical and Revision.
	2 <sup>ND</sup>	<b>CLASS TEST-II</b>
	3 <sup>RD</sup>	Short Revision and doubt clearing class of Unit-I
	4 <sup>TH</sup>	Short Revision and doubt clearing class of Unit-II
	5 <sup>TH</sup>	Short Revision and doubt clearing class of Unit-III
14 <sup>TH</sup>	1 <sup>ST</sup>	Short Revision and doubt clearing class of Unit-IV
	2 <sup>ND</sup>	Short Revision and doubt clearing class of Unit-V
	3 <sup>RD</sup>	Short Revision and doubt clearing class of Unit-VI
	4 <sup>TH</sup>	Short Revision and doubt clearing class of Unit-VII
	5 <sup>TH</sup>	Short Revision and doubt clearing class of Unit-VIII
15 <sup>TH</sup>	1 <sup>ST</sup>	Previous Year Question Discussion
	2 <sup>ND</sup>	Previous Year Question Discussion
	3 <sup>RD</sup>	Previous Year Question Discussion
	4 <sup>TH</sup>	Previous Year Question Discussion
	5 <sup>TH</sup>	Previous Year Question Discussion
16 <sup>TH</sup>	1 <sup>ST</sup>	Previous Year Question Discussion
	2 <sup>ND</sup>	Previous Year Question Discussion
	3 <sup>RD</sup>	Previous Year Question Discussion
	4 <sup>TH</sup>	Previous Year Question Discussion
	5 <sup>TH</sup>	Previous Year Question Discussion

Sign. of Faculty Concerned

*Dharmesh* 22-12-25

*for* Sign. of HOD

*Dharmesh* 22-12-25